

Time domain construction of acoustic scattering by elastic targets through finite element analysis

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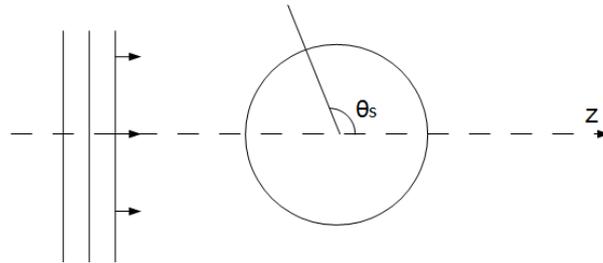
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COMSOL
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Background: Acoustic target scattering problems

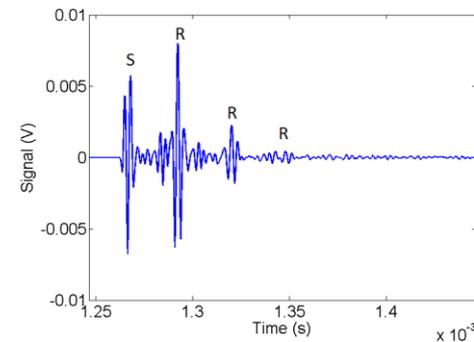
- Applicable to problem of underwater target detection/classification
- Very few known analytic solutions
 - Sphere, infinite cylinder...



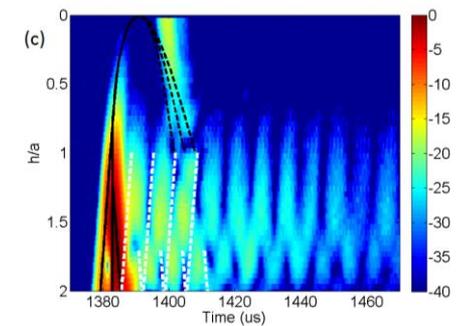
- Modeling techniques include
 - FEM, Ray theory, Kirchhoff approx., propagation models...
- Most data-model comparisons appear in the frequency (F.D.) rather than time domain (T.D.)

Advantages of a time domain model

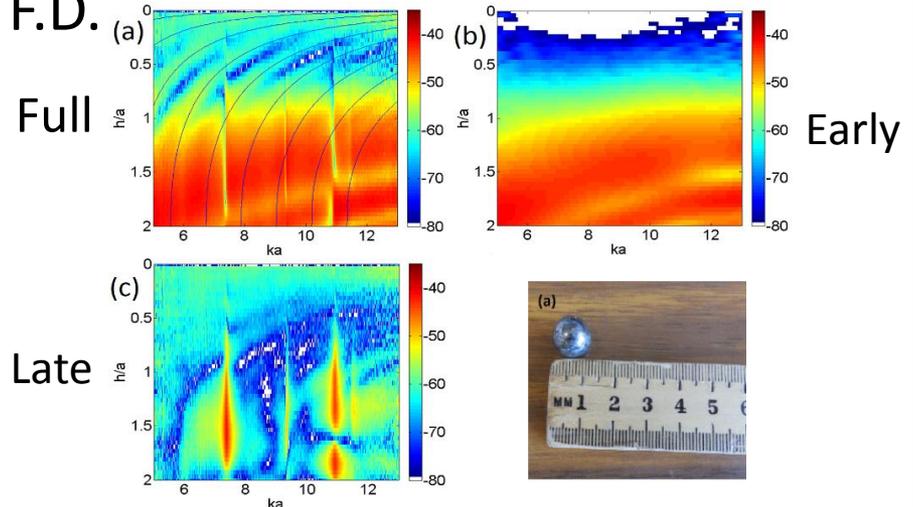
- Experimental data naturally obtained in time domain
 - In situ data/model comparison



- T.D. useful for separation/isolation of distinct arrivals which often interfere in F.D.



Time domain

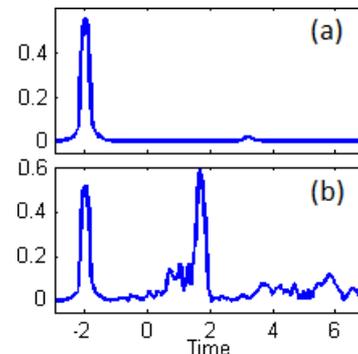


[Gunderson and Marston, JASA **140**, 3582-3592 (2016)]

Finite element models (COMSOL)

- High fidelity, wide applicability
- COMSOL capable of solving full 3D model for any target in any environment
- Fourier synthesis can be used to transform result to time domain
 - Fine frequency sampling → Long time window
 - Wide frequency range → Better time resolution

- Problem: Elastic ringing



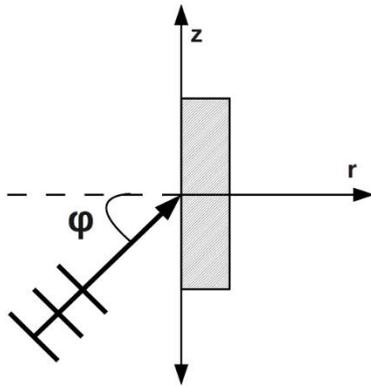
Rigid sphere

Elastic (Cu) sphere

[Exact solution: Marston, JASA **122**, 247-252 (2007)]

Axial wavenumber decomposition (AWD)

- Uses 2D geometry for 3D axisymmetric targets



- 1) Decompose incident field into Fourier components

$$p_{inc}(r, \theta, z) = \sum_{m=-\infty}^{\infty} [p_m(r, z) \exp(-im\theta)]$$

- 2) The m'th component is given by

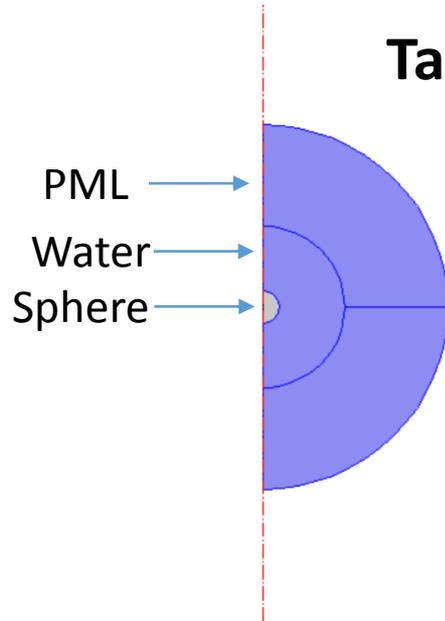
$$p_m(r, z) = (i^m) \exp(-ikz \sin \phi) J_m(-kr \cos \phi)$$

- 3) Solve a series of 2D COMSOL problems, each with a different incident component $p_m(r, z)$.
- 4) Compose full 3D scattered field, analogous with 1)

[Zampolli et. al., JASA **122**, 1472-1485 (2007)]

[Bonomo and Isakson, Proc. COMSOL Conf., Boston (2016)]

COMSOL: Problem setup



Target: User-input weak-form PDE interface

- COMSOL's built-in elastic domain interface inconsistent with AWD

$$\int_{\Omega_s} (-\omega^2 \rho_s u_i \delta u_i + \sigma_{ij} \delta \epsilon_{ij}) d\Omega - \int_{\partial\Omega_s} t_i \delta u_i dS = 0$$

[Zampolli et. al., JASA **122**, 1472-1485 (2007)]

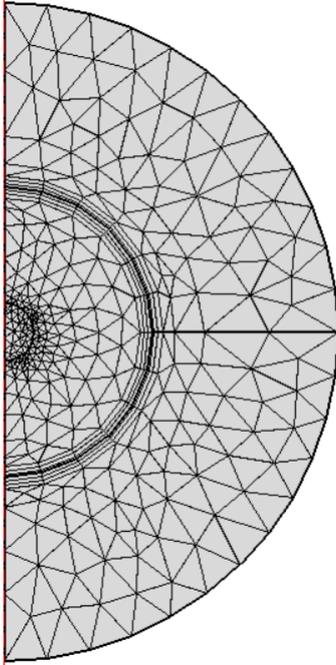
Water: Fluid: Pressure Acoustics, Freq. Domain (Acoustics mod.)

- Incident plane wave constructed through AWD, applied as a background pressure field

Perfectly Matched Layer (PML): COMSOL built-in feature

- Enforces Sommerfeld radiation condition
- Absorbs outgoing energy at near-normal incidence
- Thickness of at least one acoustic wavelength in water, λ_f

Mesh and far-field calculation



Mesh: Free triangular

- Maximum element size: $\lambda_f/6$
- Thin boundary layers at interfaces, $\sim\lambda_f/60$

Far-field calculation: COMSOL built-in tool

- Evaluated using solution at PML inner boundary

Far-field results: Exported to MATLAB through LiveLink script

Near-field results: Solution interpolated onto a pre-designed grid in MATLAB using LiveLink's "mphinterp" command

Loop structure and Fourier synthesis

Inner loop: Axial wavenumber decomposition (COMSOL)

- Loop over m from $\{-m_{max}, m_{max}\}$, $m_{max} = 1.6k(\lambda_f + a)|\cos \phi|$ *
- Export results to MATLAB, interpolate (for near-field), sum over m

Outer loop: Frequency step (MATLAB/Livelink)

- Frequency range, step size chosen to balance computational time demand against needs for time domain duration, step size
- Typical frequency range was $ka = 1 - 35$

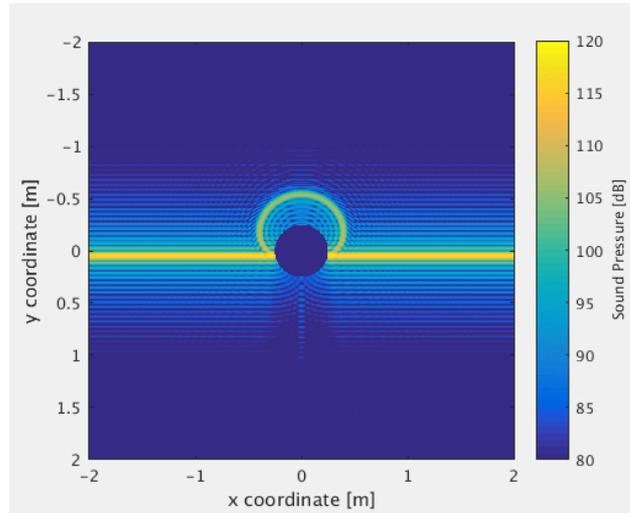
Final step: Fourier synthesis (MATLAB/Livelink)

- MATLAB's inverse fast Fourier transform "ifft" command
- Time window determined by the relations:

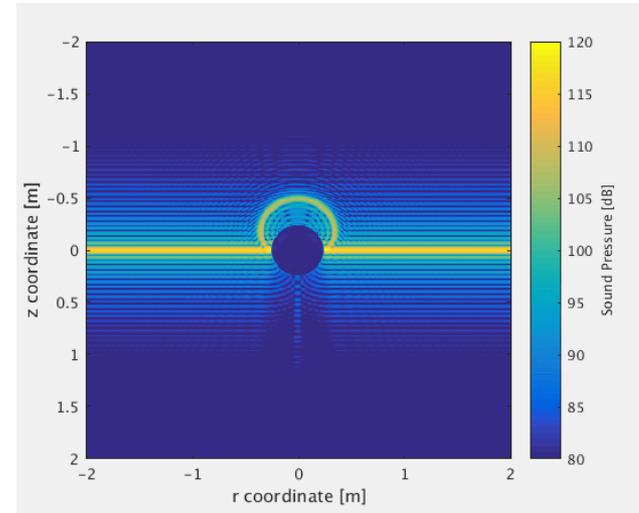
$$dt = 1/f_{max} , \quad t_{max} = (N - 1)dt$$

*[Ihlenburg, Finite Element Analysis of Acoustic Scattering, Springer-Verlag (1998)]

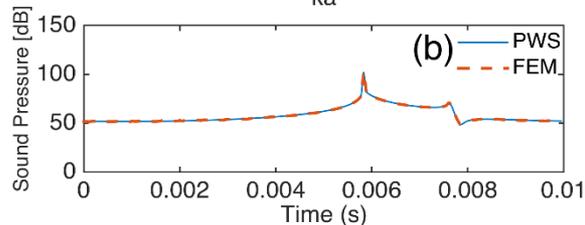
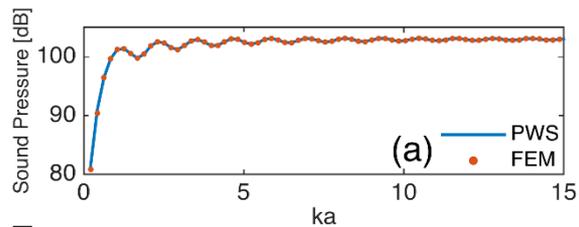
Rigid sphere near field solution



PWS (Exact)



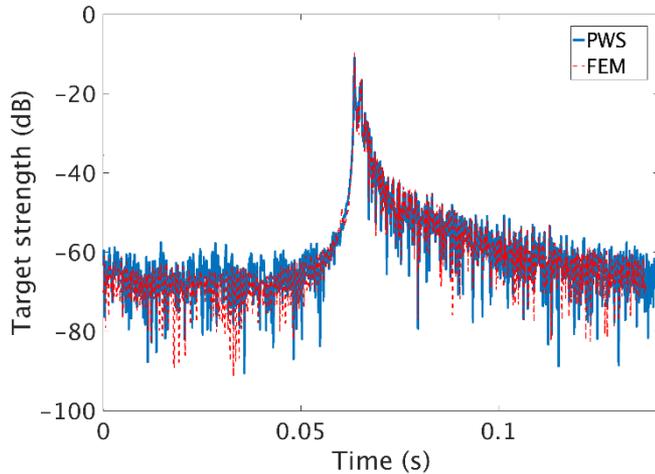
FEM



Partial Wave Series (PWS):
[Morse and Ingard, *Theoretical Acoustics*, 418-419 (1968)]

Backscattering at $r = 1.5$ m

Aluminum sphere far field solution

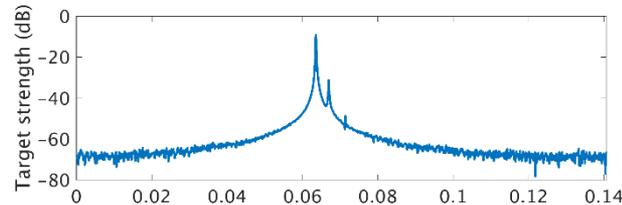


Partial wave series (PWS):
[Marston, JASA **122**, 247-252 (2007)]

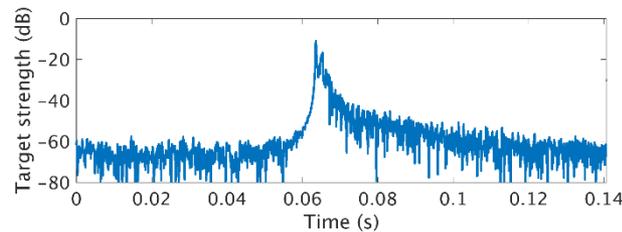
Target strength:

$$TS = 20 \log_{10} [r |p_{scat}(r, \theta, z)| / (r_0 |p_{inc}(r, \theta, z)|)]$$

Backscattering



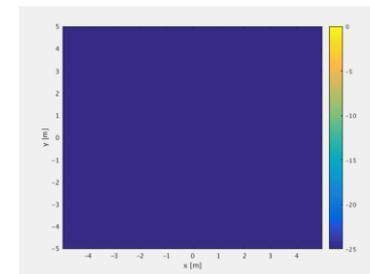
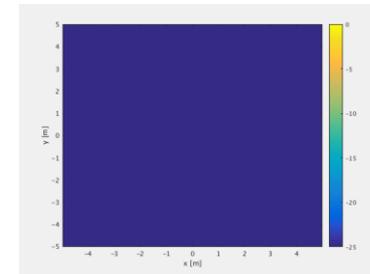
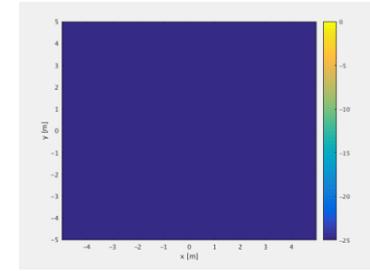
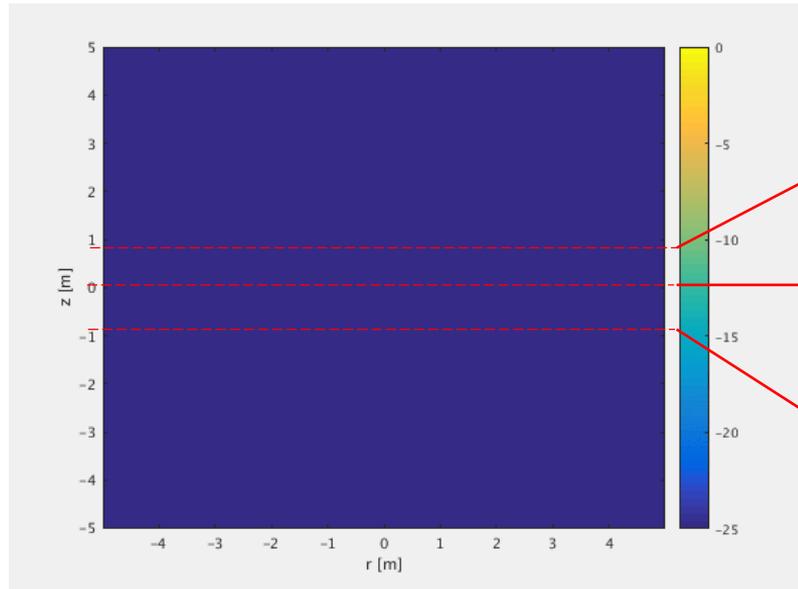
Rigid



Aluminum

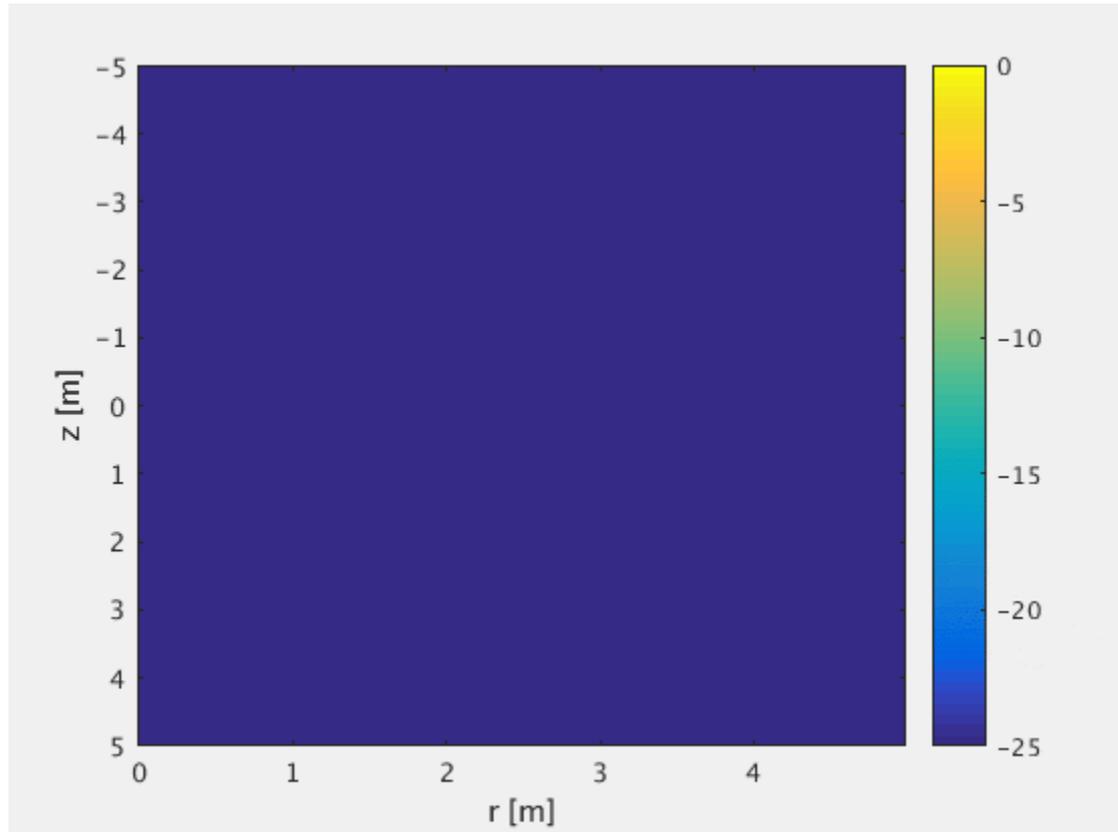
Backscattering

Aluminum sphere near field solution

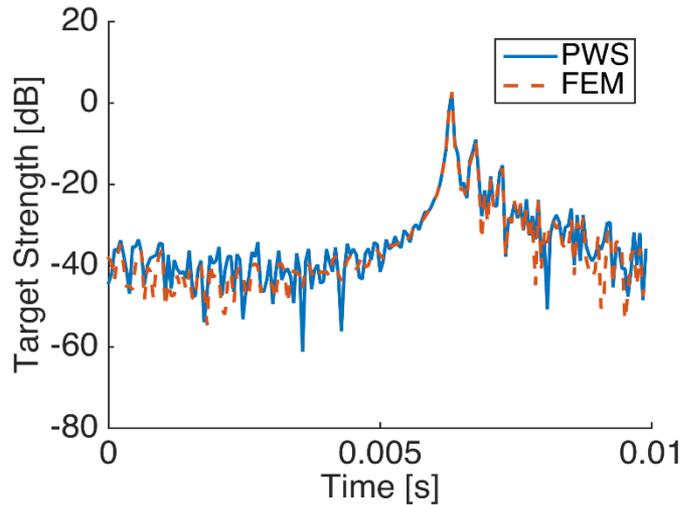


Horizontal slices

Aluminum sphere off-axis incidence



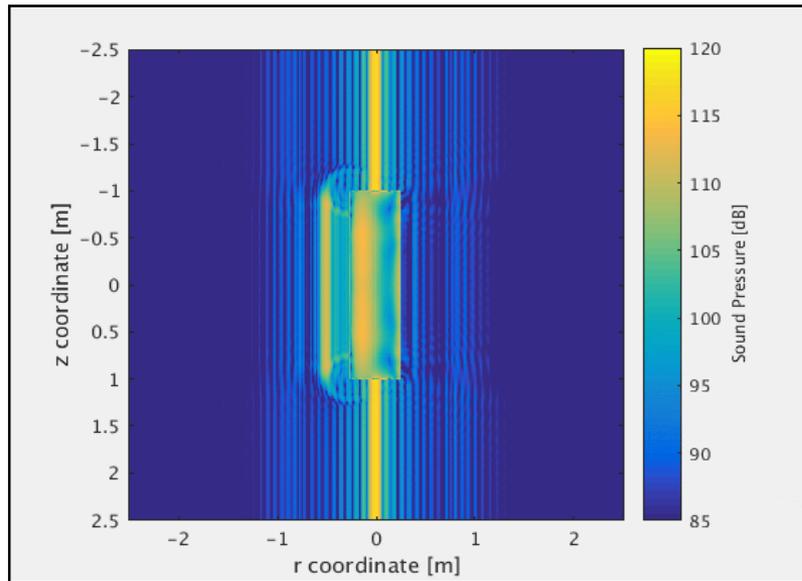
4:1 steel cylinder far field solution



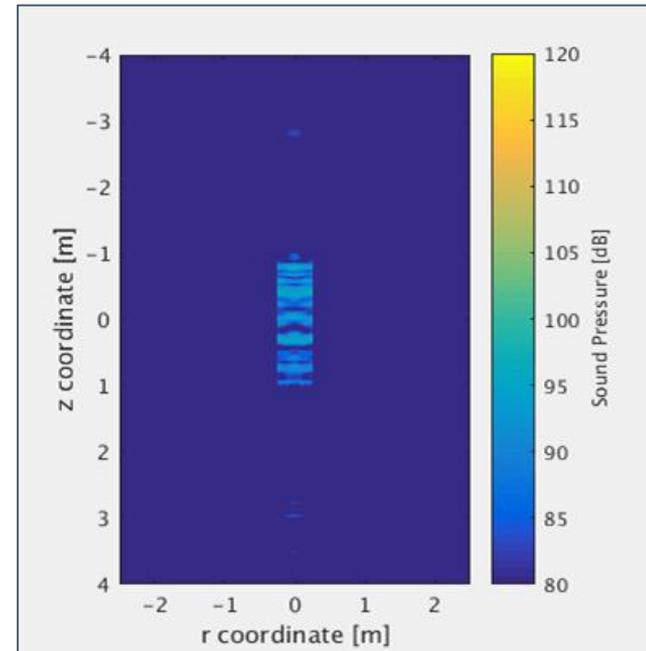
Partial wave series (PWS, approximate):
[Stanton, JASA **83**, 64-67 (1988)]

Backscattering
Broadside incidence

4:1 steel cylinder near field solution



Broadside incidence



End-on incidence

Conclusions

- Time domain models obtainable through Fourier synthesis of FEM results
- FEM results widely applicable and highly exact
 - Useful for data/model comparisons
- FEM can provide the closest thing to an exact solution

Future Work

- Introduce boundaries (seafloor)
- Apply to more complicated targets and environments → Full 3D