



Thermal-Electrical Study of an Ultra-fast Disconnect Switch with a Piezoelectric Actuator

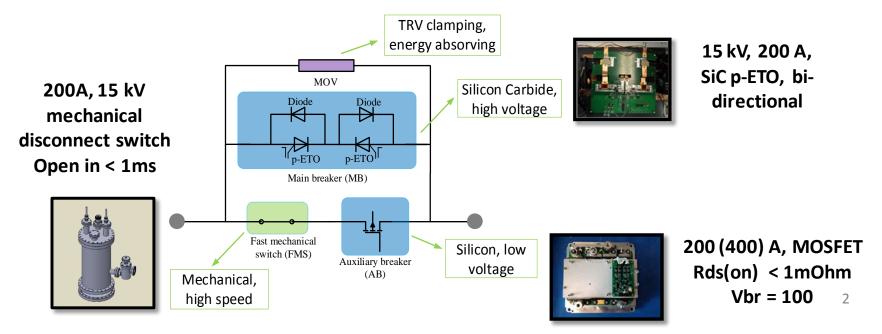
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- Hybrid circuit breakers
 - Low conduction losses by bypassing the semiconductors
 - Only as fast as the mechanical switch
 - No arcing in the mechanical switch



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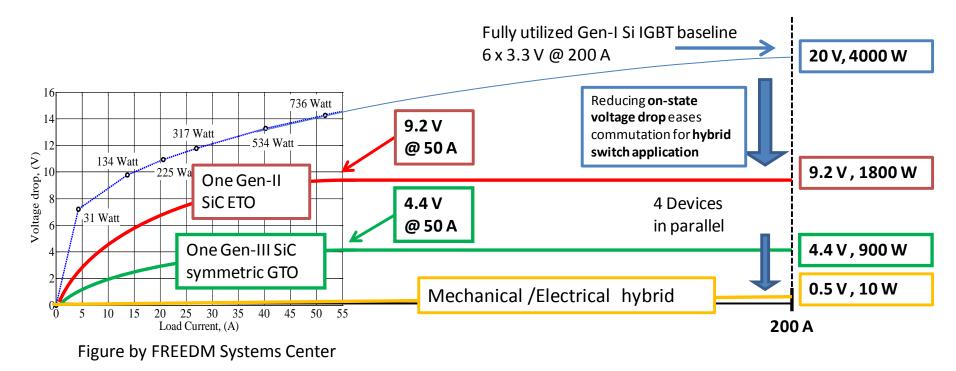
CONFERENCE



Need for a High Speed Mechanical Disconnect Switch



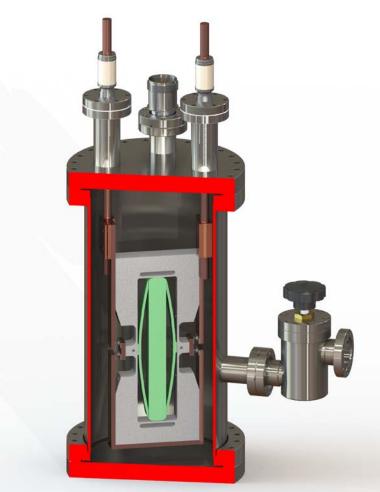
- The conduction losses drop:
 - From 4 kW to 1.8 kW by using SiC ETOs instead of Si IGBTs
 - From 1.8 kW to 900 W by using advanced symmectric GTOs
 - From 900 W to 10 W by adding a mechanical switch





Design of the Switch





Patents pending

15 kV_{RMS}, 200 A

Opening in < 1 ms •

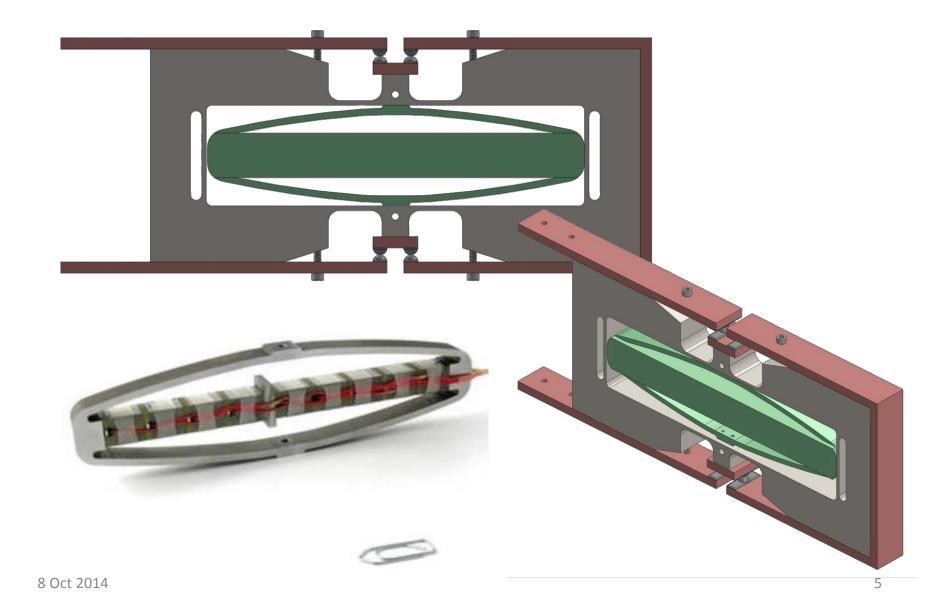
Losses in on-state: < 5 W

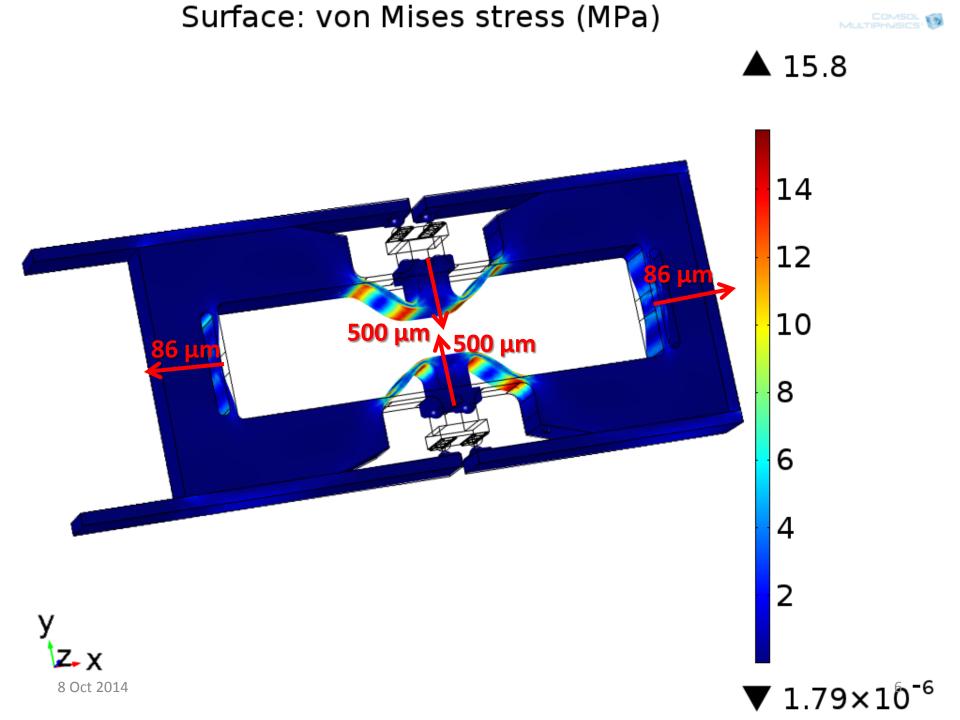


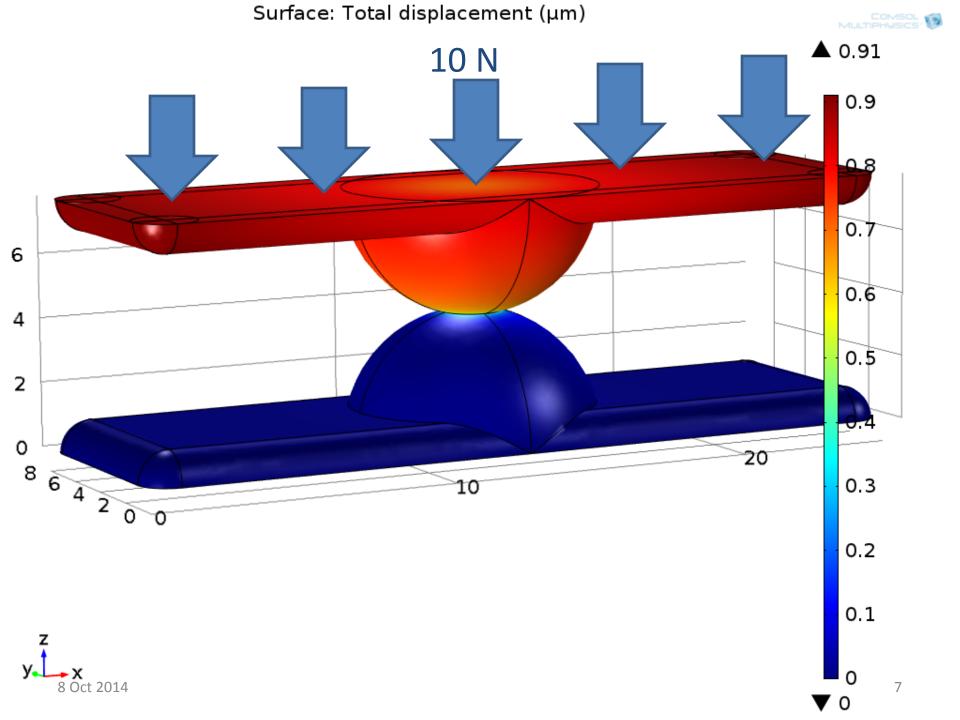


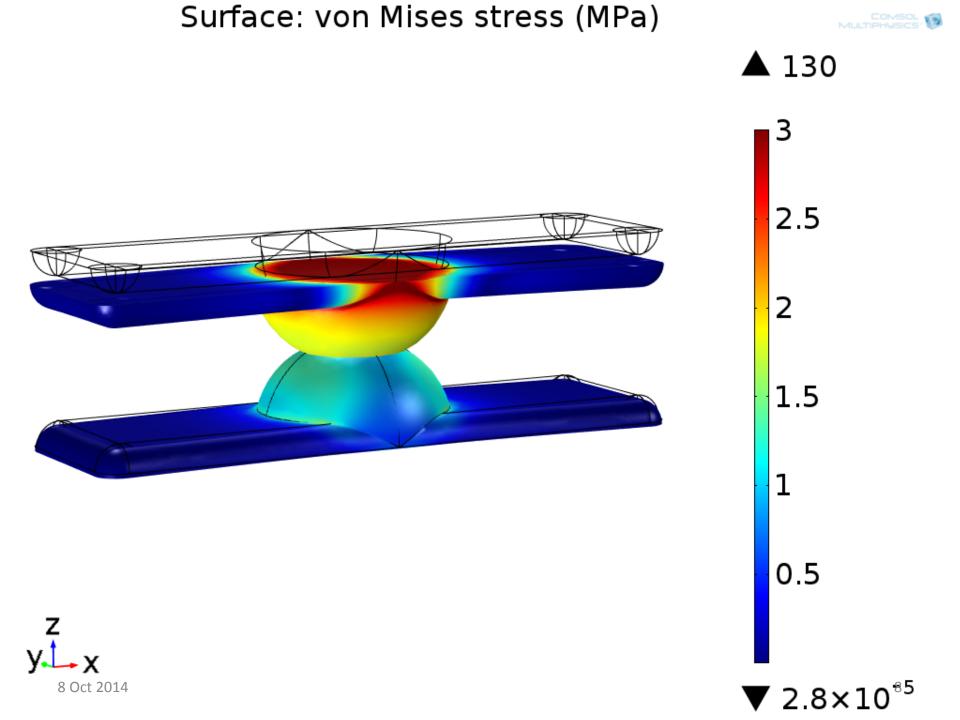
Actuator and Frame





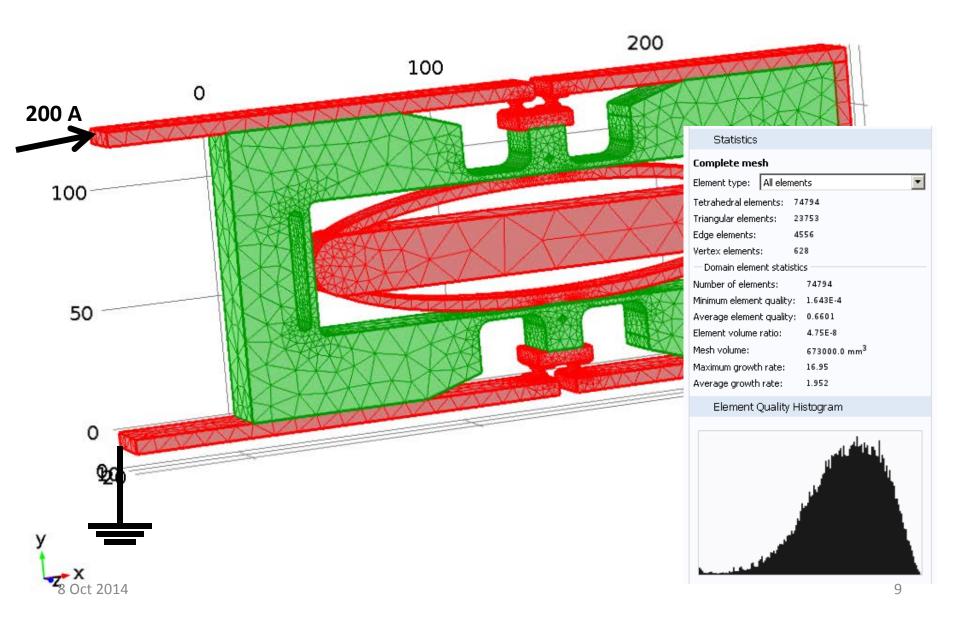






Mesh

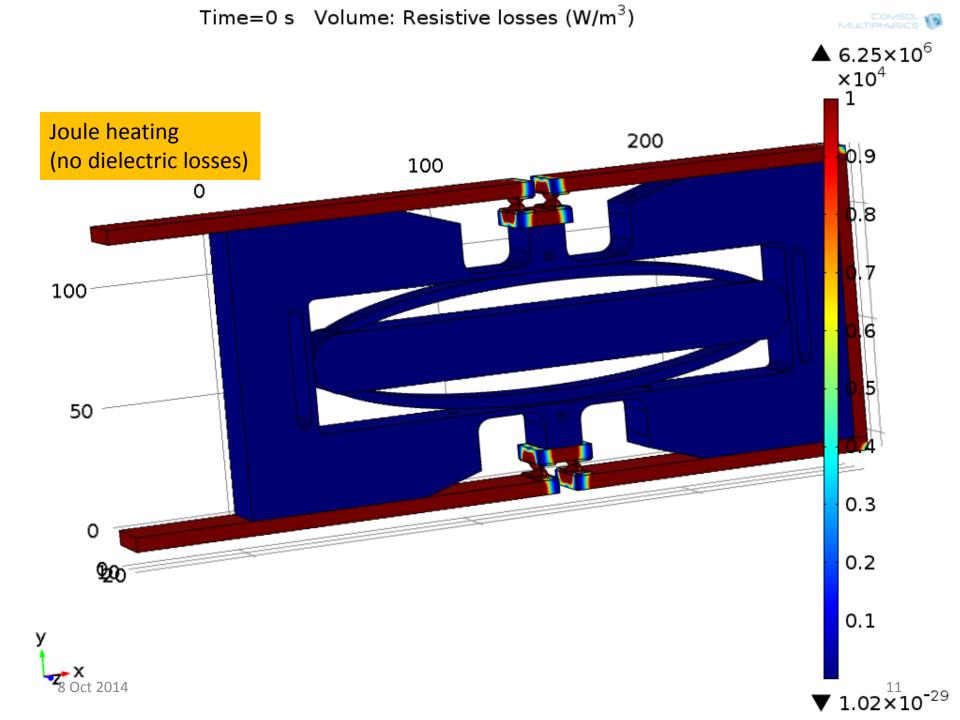
• Terminated with ground at the end of the "current path"

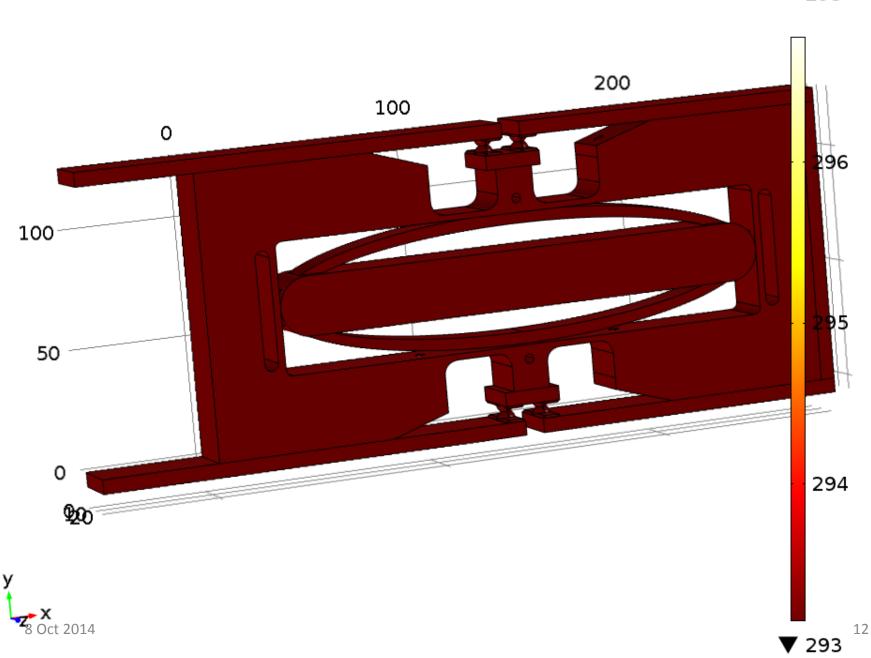


Time=0 s Multislice: Electric potential (mV)



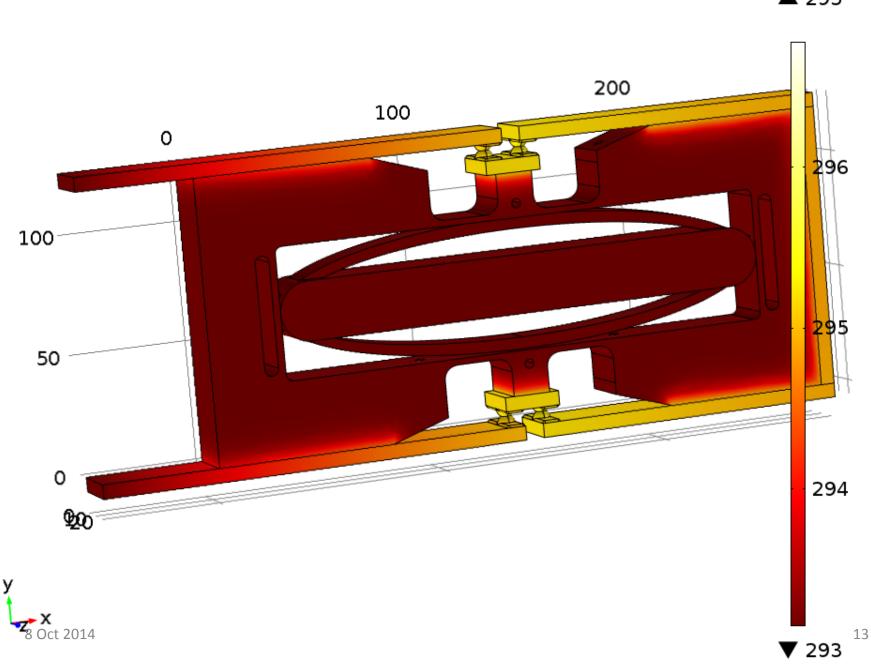
Current 200 A **A** 26.9 Contact resistance for solder joints and contact tabs (thin resistive layer) 25 Surface to ambient emissivity lacksquare0.85 (in vacuum) 20 15 10 5 $R = \frac{26.6 \,\mathrm{mV}}{200 \,\mathrm{A}} = 133 \,\mu\Omega$ Measured: ~7 W $P_{tot} = 5.32 \, \text{W}$ Oct 2014 ▼-3.55×10





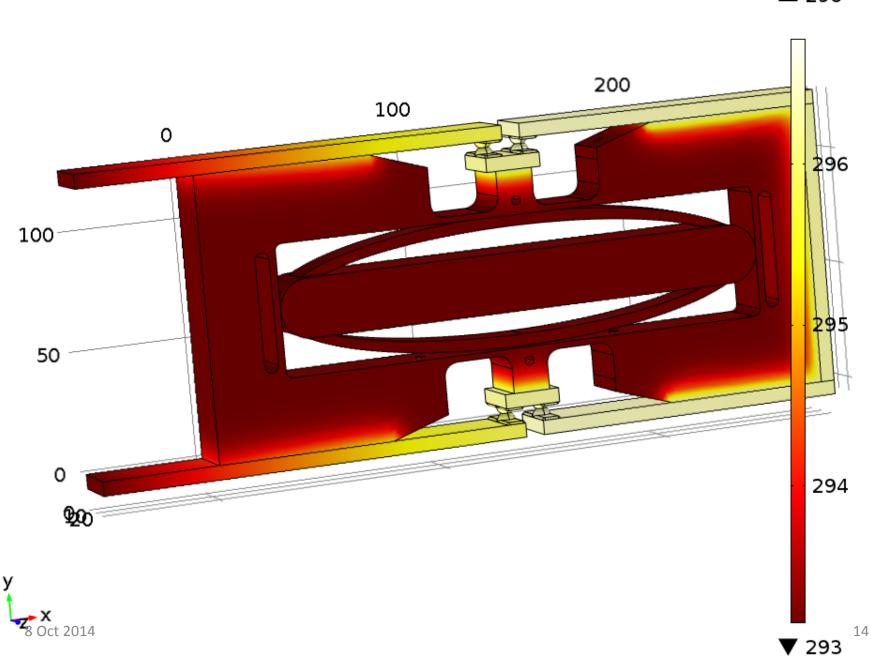
Time=0 s Surface: Temperature (K)

A 293



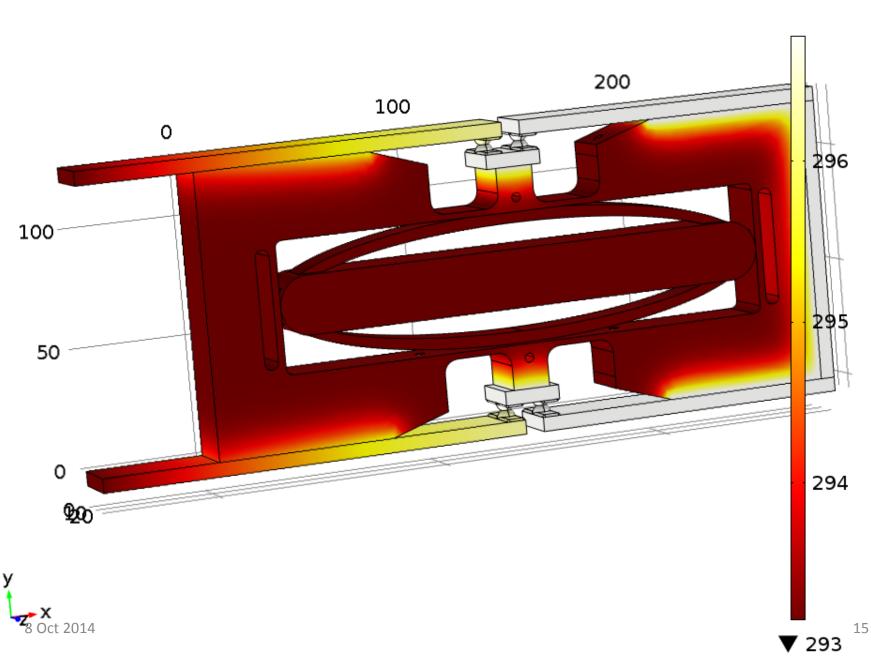
Time=200 s Surface: Temperature (K)





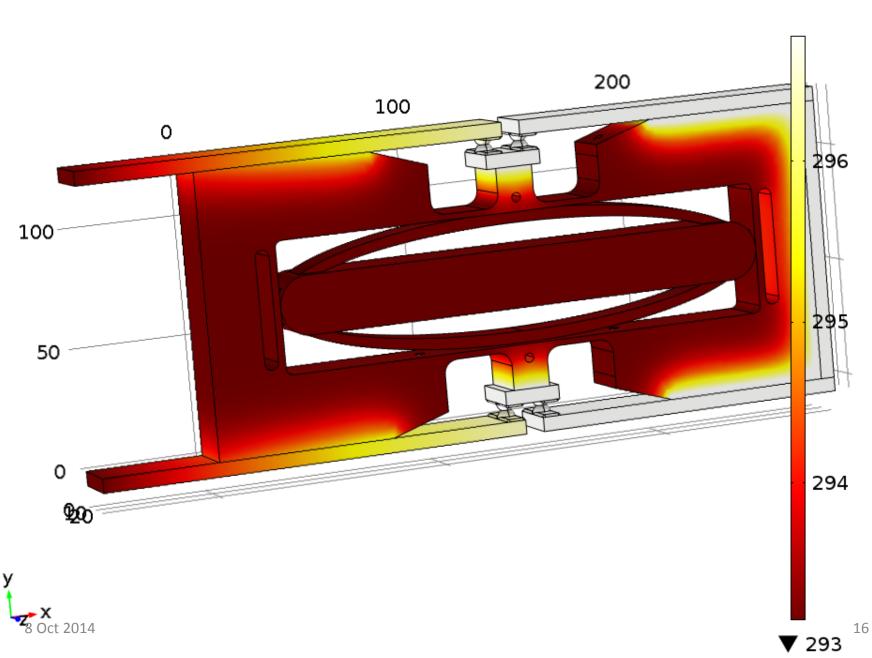
Time=400 s Surface: Temperature (K)

A 296



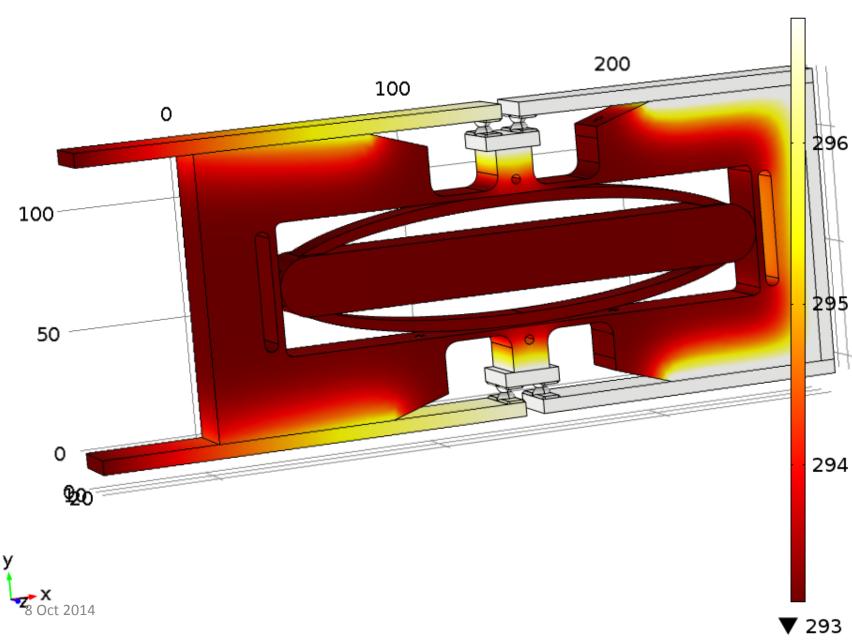
Time=600 s Surface: Temperature (K)





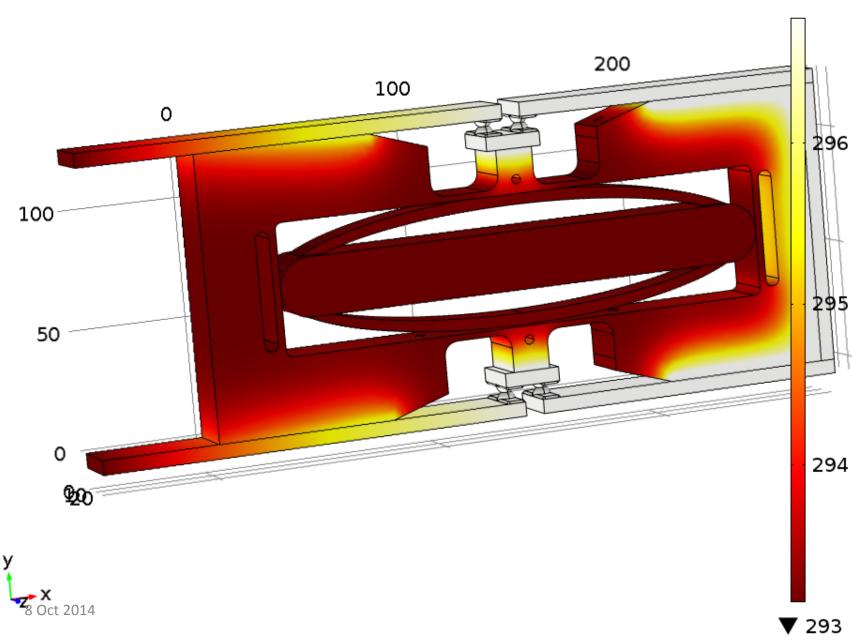
Time=800 s Surface: Temperature (K)





Time=1000 s Surface: Temperature (K)

A 298

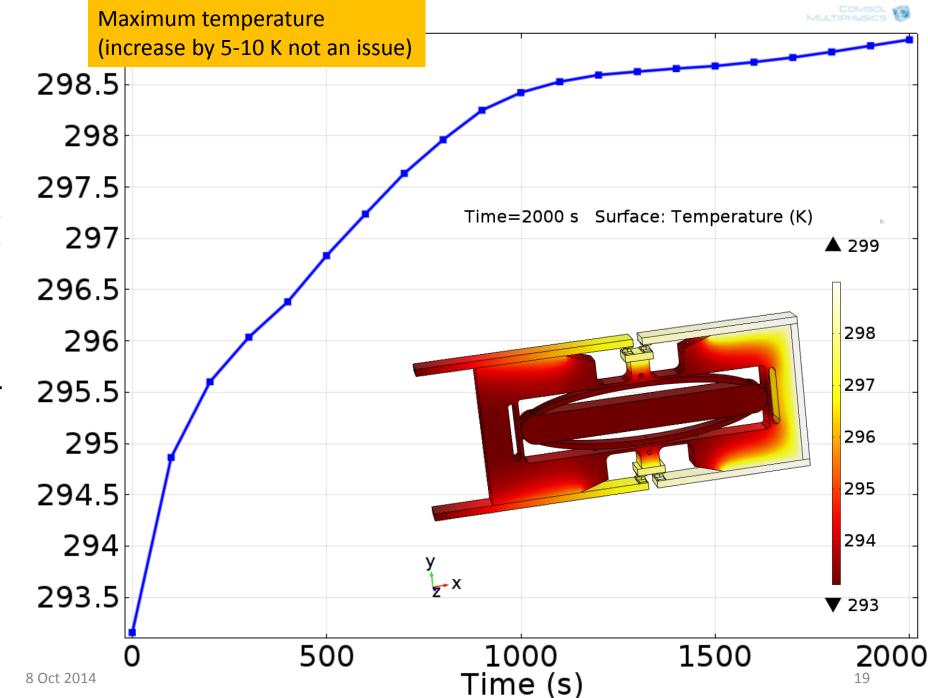


A 298

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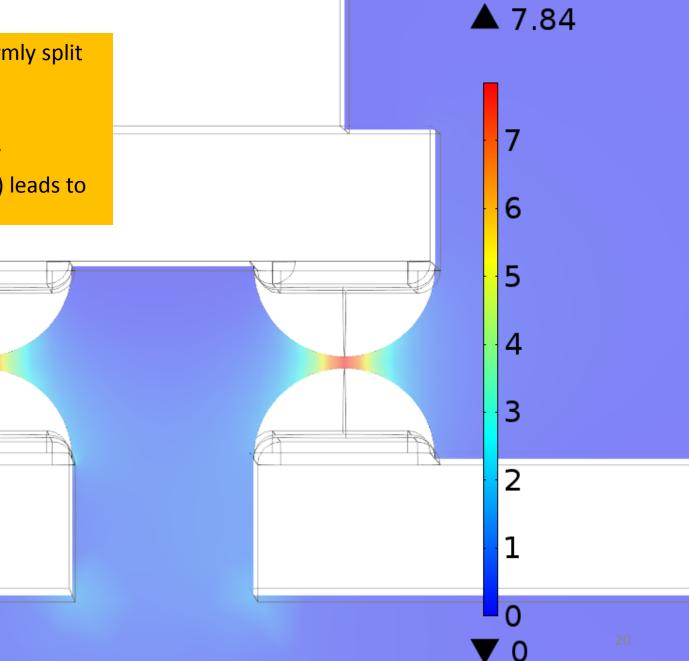
Time=1200 s Surface: Temperature (K)



Temperature (K)







- Assuming 15 kV uniformly split
- Contacts separated

Z→ X

- Mesh density refined
- Work function ~4.5 eV (or 1000 kV/mm at RT) leads to field emission

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Conclusion



• Finite element analysis proved to be useful for

- Design of insulator frame (narrow regions)
- Dimensions of conductors
- Material selection (especially contact tabs)

• Next steps

- Implement dynamic model (contact bouncing?)
- Implement more accurate, multiphysical contact model
- Validate model by measuring strain and temperature increase
- Finish demonstrator unit



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