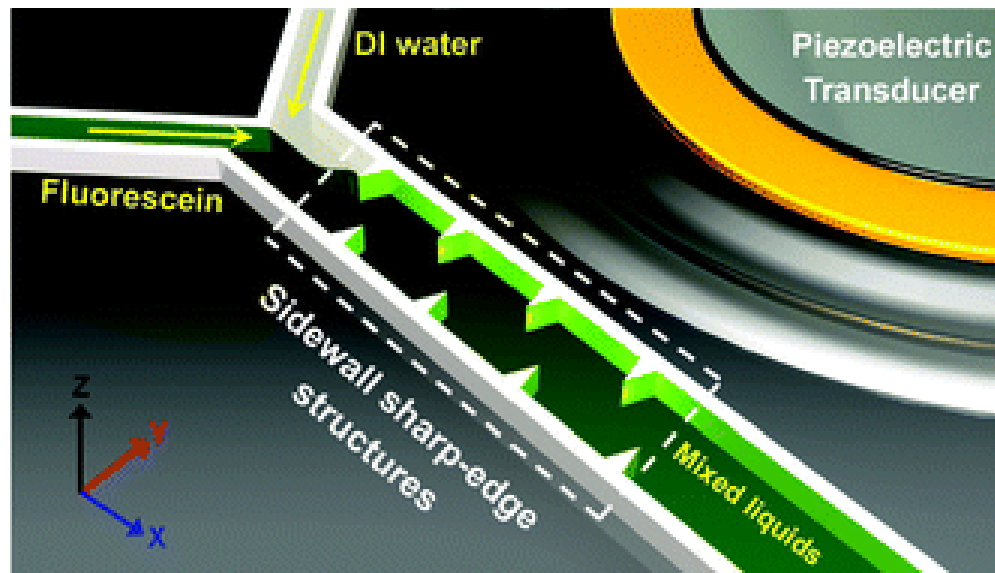


## Acoustic Streaming Driven Mixing



**Nitesh Nama, Po-Hsun Huang, Francesco Costanzo, and Tony Jun Huang**

*Department of Engineering Science and Mechanics  
The Pennsylvania State University, State College, PA, USA*

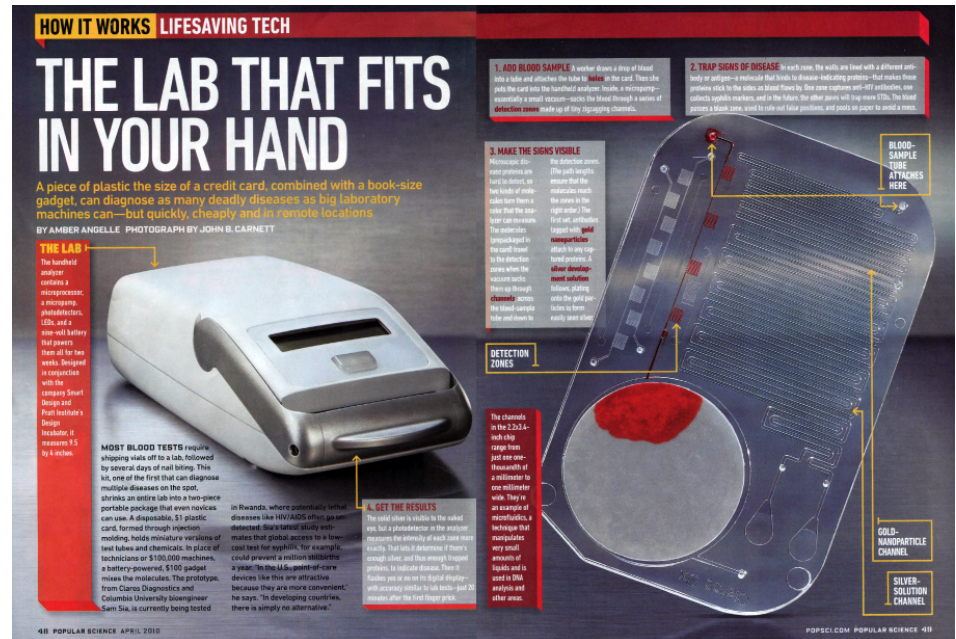
# Outline

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- **Motivation**
- **Introduction to sharp-edge based micromixer**
- **Numerical scheme**
- **COMSOL Modeling and convergence**
- **Results**
- **Conclusion and Outlook**

# Motivation – Lab on a chip

**Lab on a chip (LOC)** – A device that integrates one or several of the laboratory functions onto a small chip.



- Low-cost.
- Faster results.
- Low sample consumption.
- Point-of-care diagnostics.
- Ease of operation.

# Microfluidics towards lab-on-a-chip

## Common functionalities needed:

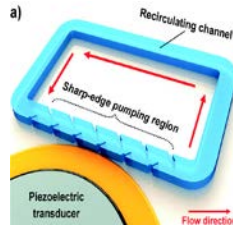
- Fluid manipulation

- Mixing



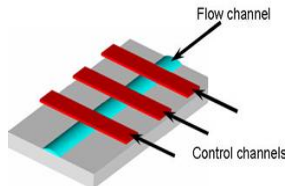
Kwona et al, *Tetrahedron Letters*, 2008

- Pumping



Huang et al, *Lab on a Chip*, 2014.

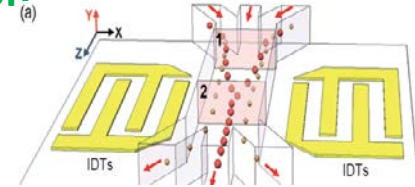
- Valves



Melin et al, *Ann. Rev. Biophys.*, 2007.

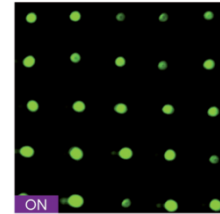
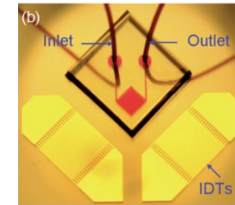
- Particle/Cell manipulation

- Separation



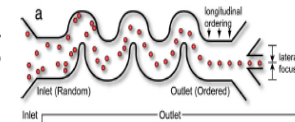
Shi et al, *Lab on a Chip*, 2009.

- Patterning

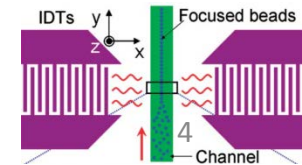


Shi et al, *Lab on a Chip*, 2009.

- Focusing



Di Carlo, *PNAS*, 2007.



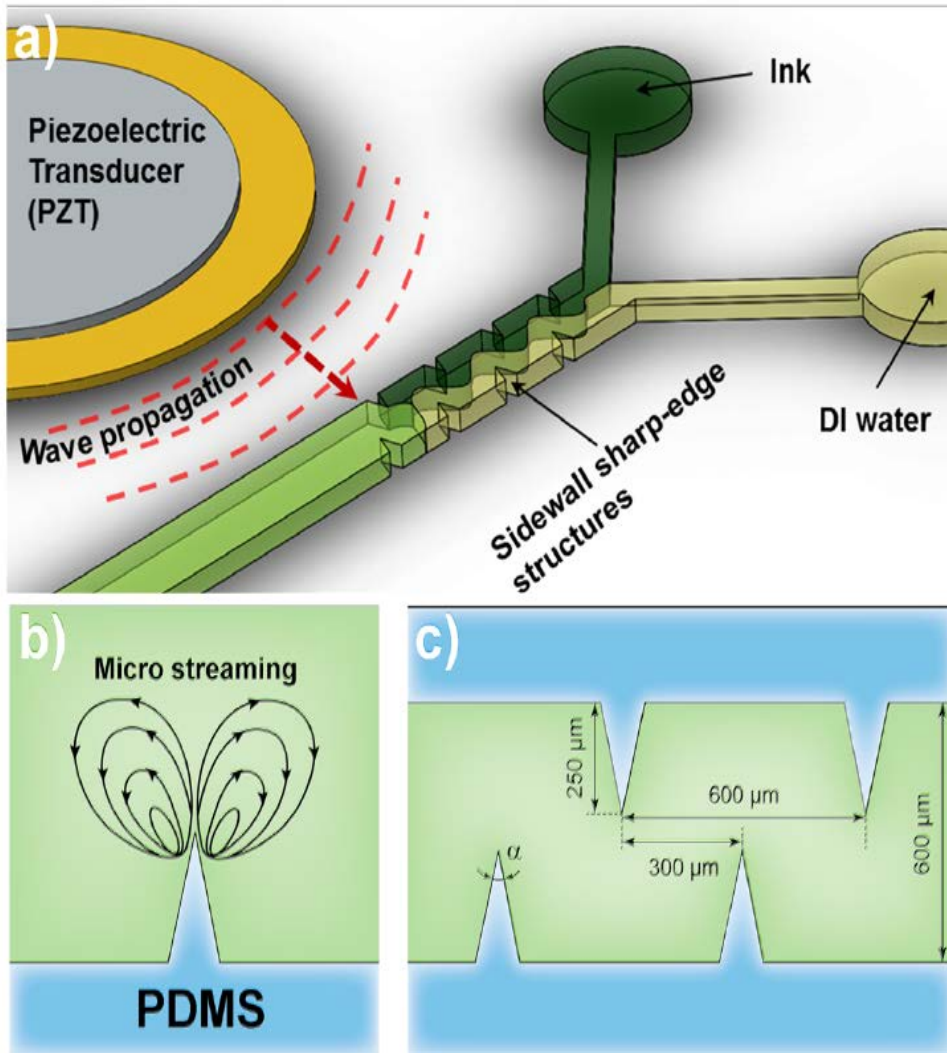
Shi et al, *Lab on a Chip*, 2007.

## Challenges at microscales:

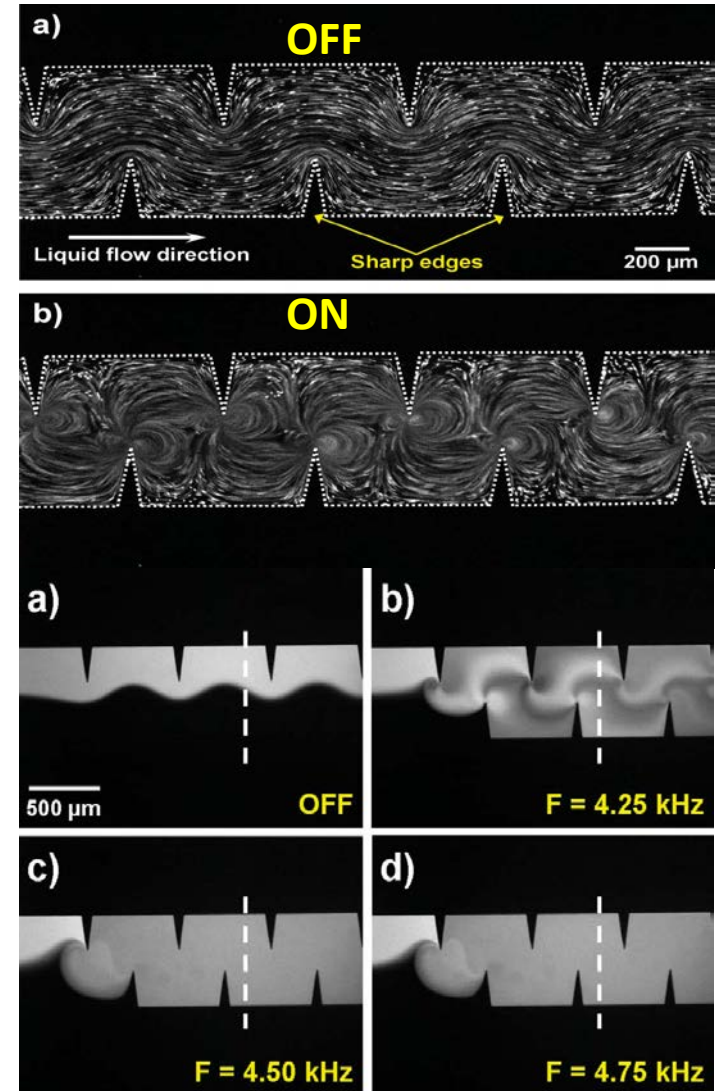
- Low Reynolds number → Slow diffusion dominated mixing

- Difficult fluid pumping  $\Delta P = \frac{8\mu LQ}{\pi r^4}$

# Sharp-edge based microfluidic mixing



Nama et al, Lab on a Chip, 2014.



Huang et al, Lab on a Chip, 2014.

# Governing equations

---

**Balance of mass**

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

**Balance of linear momentum**

$$\rho \frac{\partial \mathbf{v}}{\partial t} + \rho (\mathbf{v} \cdot \nabla) \mathbf{v} = -\nabla p + \mu \nabla^2 \mathbf{v} + \left( \mu_b + \frac{1}{3} \mu \right) \nabla (\nabla \cdot \mathbf{v})$$

**Constitutive relation**

$$p = c_0^2 \rho$$

**Convection-Diffusion Equation**

$$\frac{\partial c}{\partial t} + \nabla \cdot (c \mathbf{v}) = D \nabla^2 c$$

**Numerical Challenges associated with direct solution:**

- Widely separated length scales – Characteristic wavelengths (1 m) vs. characteristic dimensions of microfluidic channel ( $10^{-3}$  m)
- Widely separated time scales – Characteristic oscillation period ( $10^{-4}$  s) vs. characteristic times dictated by streaming speeds ( $10^{-1}$  s)
- Direct simulations are possible, but are computationally expensive.

# Numerical Model

---

## Perturbation expansion

$$\begin{aligned}\mathbf{v} &= \mathbf{v}_0 + \varepsilon \tilde{\mathbf{v}}_1 + \varepsilon^2 \tilde{\mathbf{v}}_2 + O(\varepsilon^3) + \dots \\ p &= p_0 + \varepsilon \tilde{p}_1 + \varepsilon^2 \tilde{p}_2 + O(\varepsilon^3) + \dots \\ \rho &= \rho_0 + \varepsilon \tilde{\rho}_1 + \varepsilon^2 \tilde{\rho}_2 + O(\varepsilon^3) + \dots\end{aligned}$$

- Presence of a background laminar flow before actuation

## Zeroth-order equations

$$\begin{aligned}\frac{\partial \rho_0}{\partial t} + \rho_0 (\nabla \cdot \mathbf{v}_0) &= 0, \\ \rho_0 \frac{\partial \mathbf{v}_0}{\partial t} + \rho_0 (\mathbf{v}_0 \cdot \nabla) \mathbf{v}_0 \\ &= -\nabla p_0 + \mu \nabla^2 \mathbf{v}_0 + (\mu_b + \frac{1}{3} \mu) \nabla (\nabla \cdot \mathbf{v}_0).\end{aligned}$$

## First-order equations

$$\begin{aligned}\frac{\partial \rho_1}{\partial t} + \nabla \cdot (\rho_0 \mathbf{v}_1 + \rho_1 \mathbf{v}_0) &= 0, \\ \rho_0 \frac{\partial \mathbf{v}_1}{\partial t} + \rho_1 \frac{\partial \mathbf{v}_0}{\partial t} + \rho_0 (\mathbf{v}_1 \cdot \nabla) \mathbf{v}_0 + \rho_0 (\mathbf{v}_0 \cdot \nabla) \mathbf{v}_1 + \rho_1 (\mathbf{v}_0 \cdot \nabla) \mathbf{v}_0 \\ &= -\nabla p_1 + \mu \nabla^2 \mathbf{v}_1 + (\mu_b + \frac{1}{3} \mu) \nabla (\nabla \cdot \mathbf{v}_1).\end{aligned}$$

# Numerical Model

## Second-order equations

$$\begin{aligned} \left\langle \frac{\partial \rho_2}{\partial t} \right\rangle + \nabla \cdot (\langle \rho_0 \mathbf{v}_2 \rangle + \langle \rho_2 \mathbf{v}_0 \rangle) &= -\nabla \cdot \langle \rho_1 \mathbf{v}_1 \rangle, \\ \left\langle \rho_0 \frac{\partial \mathbf{v}_2}{\partial t} \right\rangle + \left\langle \rho_2 \frac{\partial \mathbf{v}_0}{\partial t} \right\rangle + \left\langle \rho_1 \frac{\partial \mathbf{v}_1}{\partial t} \right\rangle + \langle \rho_0 \mathbf{v}_1 \cdot \nabla \mathbf{v}_1 \rangle \\ &+ \langle \rho_0 \mathbf{v}_0 \cdot \nabla \mathbf{v}_2 \rangle + \langle \rho_0 \mathbf{v}_2 \cdot \nabla \mathbf{v}_0 \rangle + \langle \rho_1 \mathbf{v}_0 \cdot \nabla \mathbf{v}_1 \rangle \\ &+ \langle \rho_1 \mathbf{v}_1 \cdot \nabla \mathbf{v}_0 \rangle + \langle \rho_2 \mathbf{v}_0 \cdot \nabla \mathbf{v}_0 \rangle \\ &= -\nabla \langle p_2 \rangle + \mu \nabla^2 \langle \mathbf{v}_2 \rangle + (\mu_b + \frac{1}{3} \mu) \nabla (\nabla \cdot \langle \mathbf{v}_2 \rangle) \end{aligned}$$

## Convection-Diffusion Equation

$$\frac{\partial c}{\partial t} + \nabla \cdot (c \mathbf{v}) = D \nabla^2 c$$

## Mean Lagrangian Velocity

$$\mathbf{v}^L = \langle \mathbf{v}_2 \rangle + \langle (\boldsymbol{\xi}_1 \cdot \nabla) \mathbf{v}_1 \rangle$$

Stoke's Drift

$$\frac{\partial \boldsymbol{\xi}_1}{\partial t} = \mathbf{v}_1$$

## Effective convection velocity

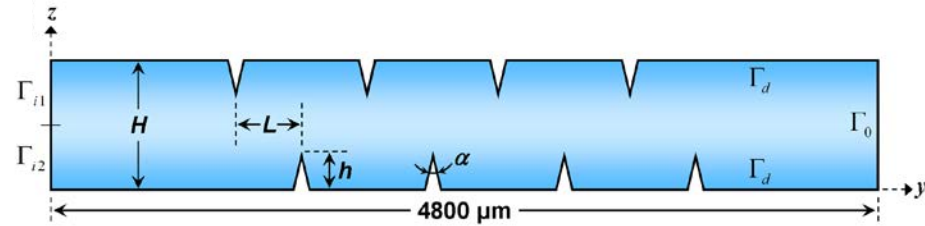
$$\mathbf{v}^C = \mathbf{v}_0 + \mathbf{v}^L$$



# Boundary Conditions

**Zeroth-order:**  $\mathbf{v}_0 = \mathbf{v}_{in}$ , on  $\Gamma_{i1} \cup \Gamma_{i2}$ .

$\mathbf{v}_0 = \mathbf{0}$ , on  $\Gamma_d$



**First-order:**

*Harmonic Displacement*

$$u_y(z) = d_0 + d_1 \left(\frac{z}{h}\right)^3$$

$$\mathbf{v}_1(t, z) = \frac{\partial \mathbf{u}(t, z)}{\partial t}, \quad \text{on } \Gamma_d$$

**Second-order:**  $\mathbf{v}_2 = \mathbf{0}$ , on  $\Gamma_d$

**Convection-Diffusion Equation:**

$$c = 0, \quad \text{on } \Gamma_{i1}.$$

$$c = 1 \text{ mol/m}^3, \quad \text{on } \Gamma_{i2}$$

*No flux at walls*

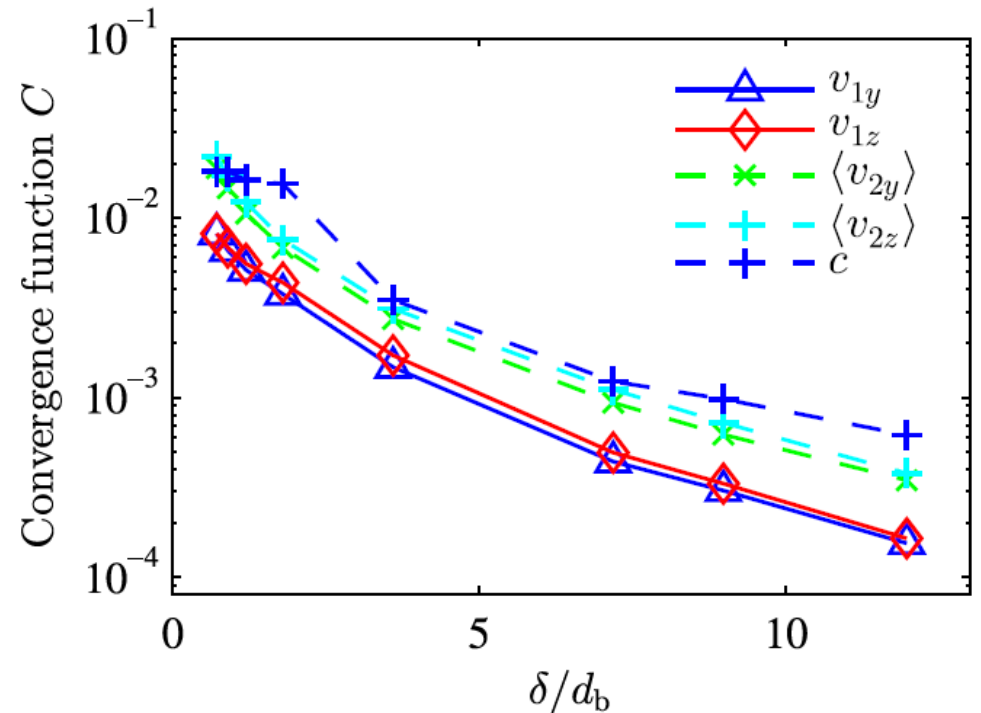
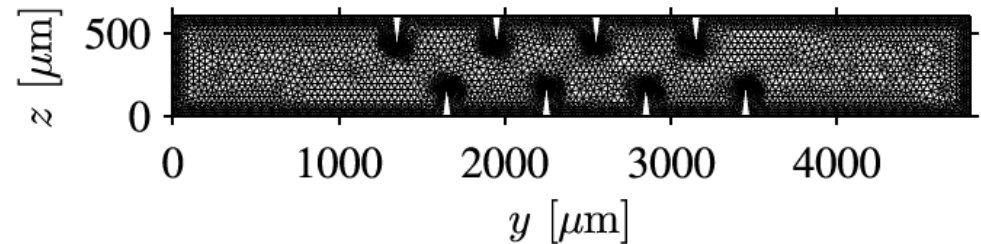
$$c\mathbf{v} = \mathbf{0}, \quad \text{on } \Gamma_d$$

*Outlet*

$$c\mathbf{v} - D\nabla c = \mathbf{0}, \quad \text{on } \Gamma_o.$$

# COMSOL Modeling and convergence

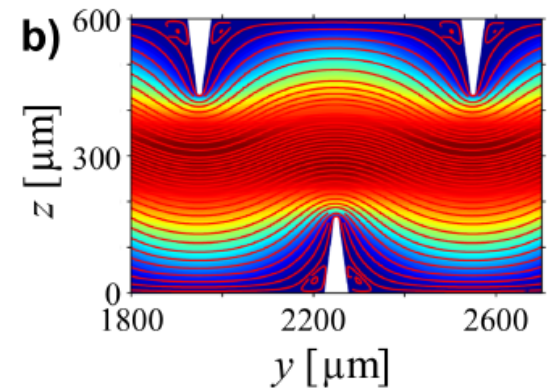
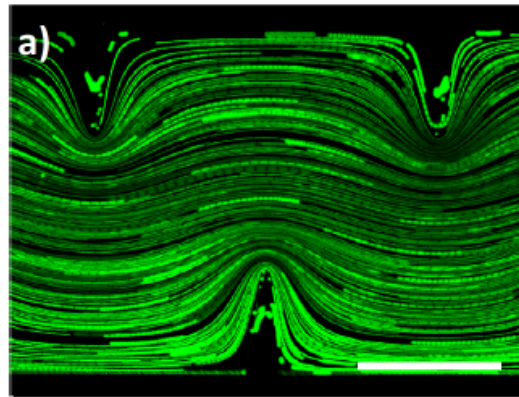
- *Weak PDE* interface
- P2/P1 elements for velocity and pressure.
- The sharp corners were rounded off with a small radius using *Fillet*
- *Parametric sweep* for the mesh size to obtain mesh convergence.
- Finer mesh near the boundaries to resolve the boundary layers.



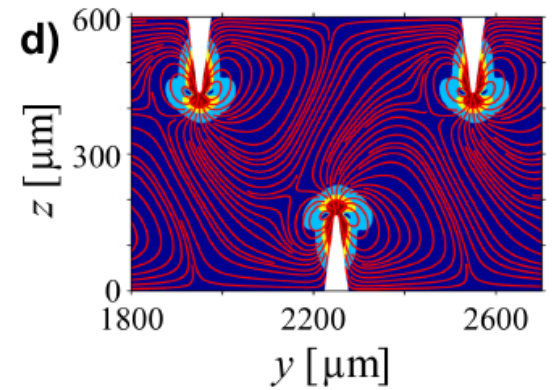
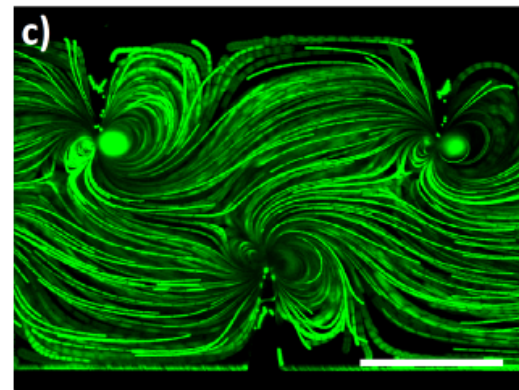
$$C(g) = \sqrt{\frac{\int (g - g_{\text{ref}})^2 dy dz}{\int (g_{\text{ref}})^2 dy dz}}$$

# Comparison with Experiments

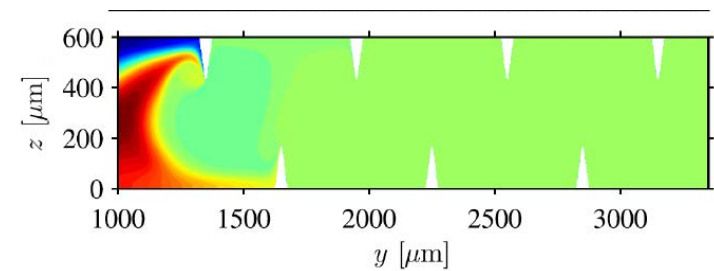
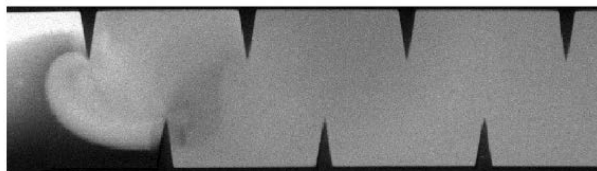
ACOUSTICS OFF



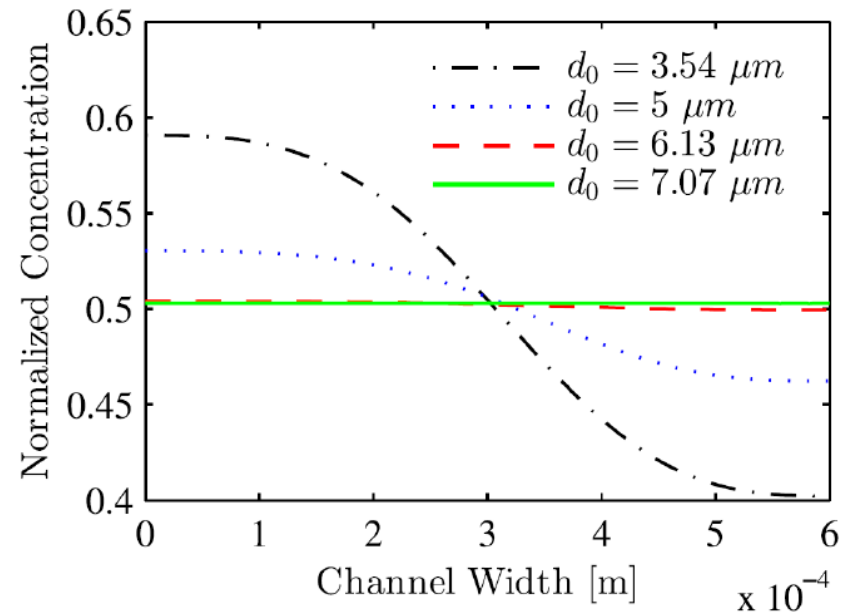
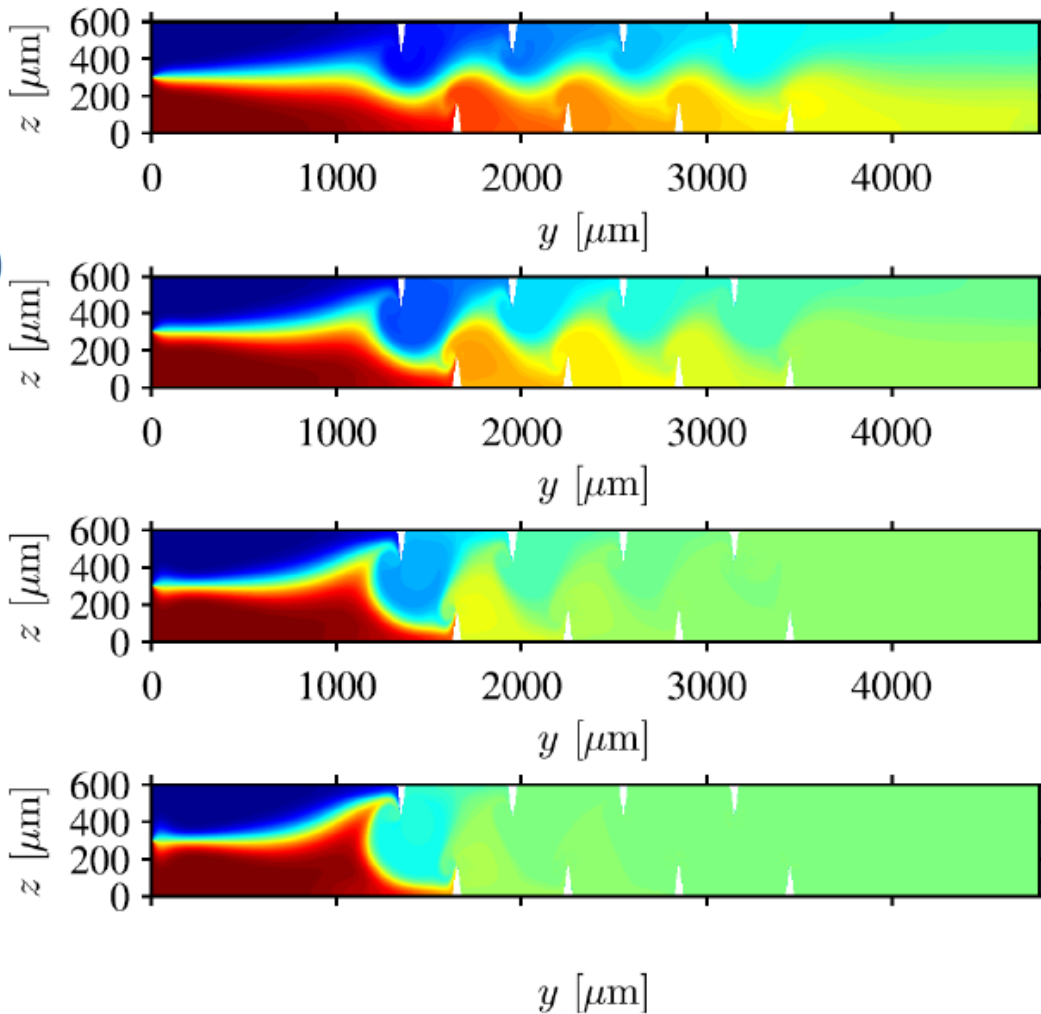
ACOUSTICS ON



CONCENTRATION PROFILE

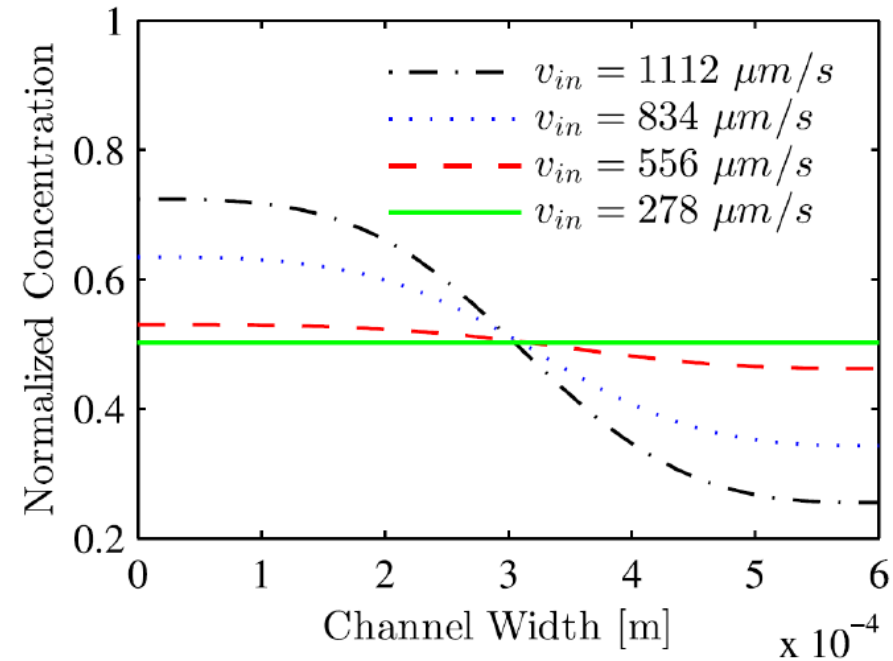
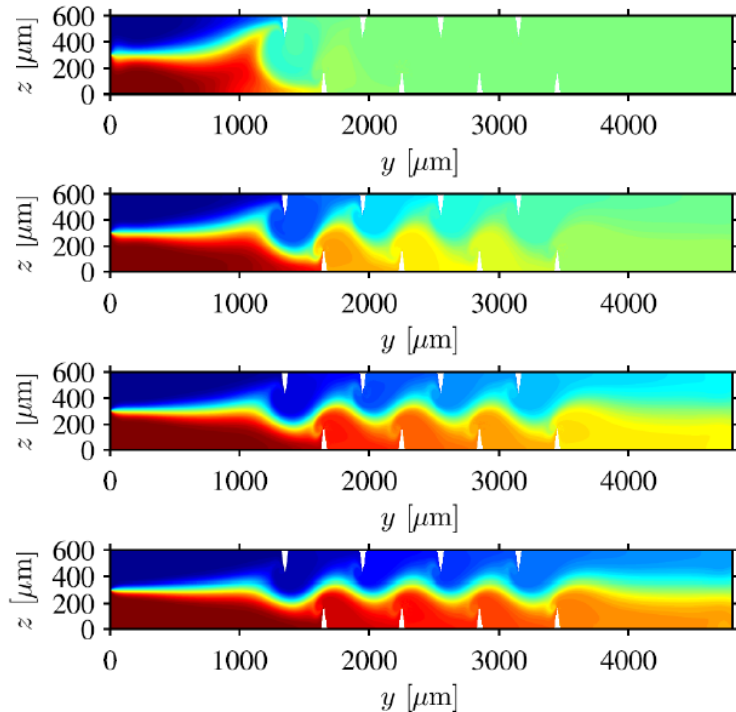


# Effect of the applied power



- High power  $\Rightarrow$  Faster mixing length  $\Rightarrow$  Ability to increase throughput for a desired mixing length

# Effect of the inlet velocity



## Second-Order Equations

$$\begin{aligned}
 \left\langle \frac{\partial \rho_2}{\partial t} \right\rangle + \nabla \cdot (\langle \rho_0 \mathbf{v}_2 \rangle + \langle \rho_2 \mathbf{v}_0 \rangle) &= -\nabla \cdot \langle \rho_1 \mathbf{v}_1 \rangle, \\
 \left\langle \rho_0 \frac{\partial \mathbf{v}_2}{\partial t} \right\rangle + \left\langle \rho_2 \frac{\partial \mathbf{v}_0}{\partial t} \right\rangle + \left\langle \rho_1 \frac{\partial \mathbf{v}_1}{\partial t} \right\rangle + \langle \rho_0 \mathbf{v}_1 \cdot \nabla \mathbf{v}_1 \rangle \\
 &+ \langle \rho_0 \mathbf{v}_0 \cdot \nabla \mathbf{v}_2 \rangle + \langle \rho_0 \mathbf{v}_2 \cdot \nabla \mathbf{v}_0 \rangle + \langle \rho_1 \mathbf{v}_0 \cdot \nabla \mathbf{v}_1 \rangle \\
 &+ \langle \rho_1 \mathbf{v}_1 \cdot \nabla \mathbf{v}_0 \rangle + \langle \rho_2 \mathbf{v}_0 \cdot \nabla \mathbf{v}_0 \rangle \\
 &= -\nabla \langle p_2 \rangle + \mu \nabla^2 \langle \mathbf{v}_2 \rangle + (\mu_b + \frac{1}{3} \mu) \nabla (\nabla \cdot \langle \mathbf{v}_2 \rangle)
 \end{aligned}$$

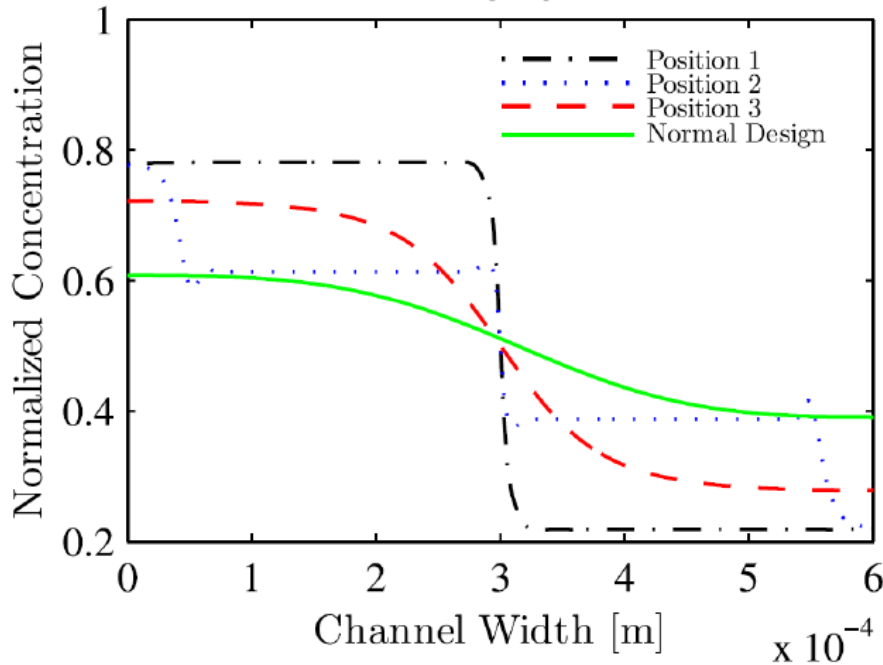
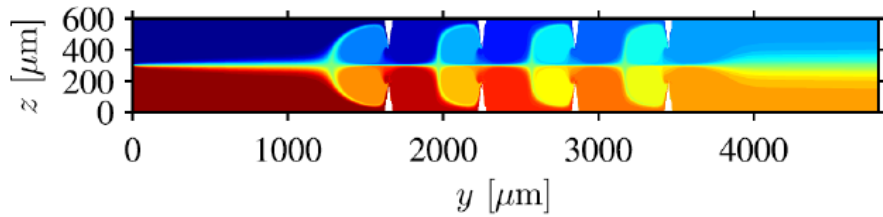
## Effective convection velocity

$$\mathbf{v}^C = \mathbf{v}_0 + \mathbf{v}^L$$

- A change in inlet velocity has an effect on both the background flow as well as the streaming flow (due to some time-averaged terms containing inlet velocity).

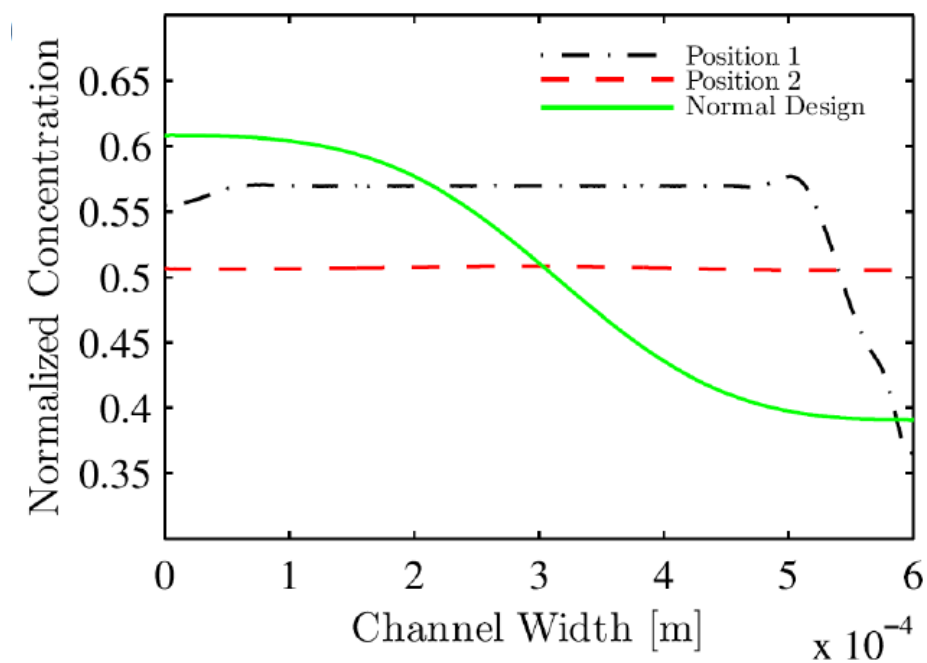
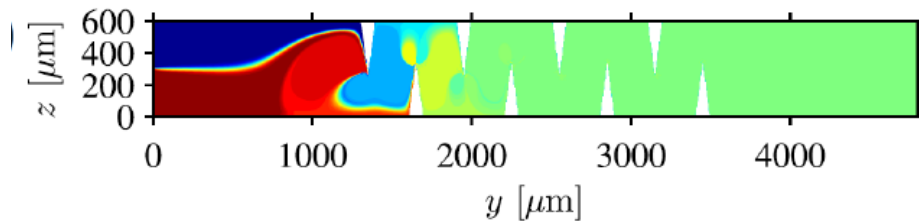
# Different Designs

## Opposite Sharp-Edges



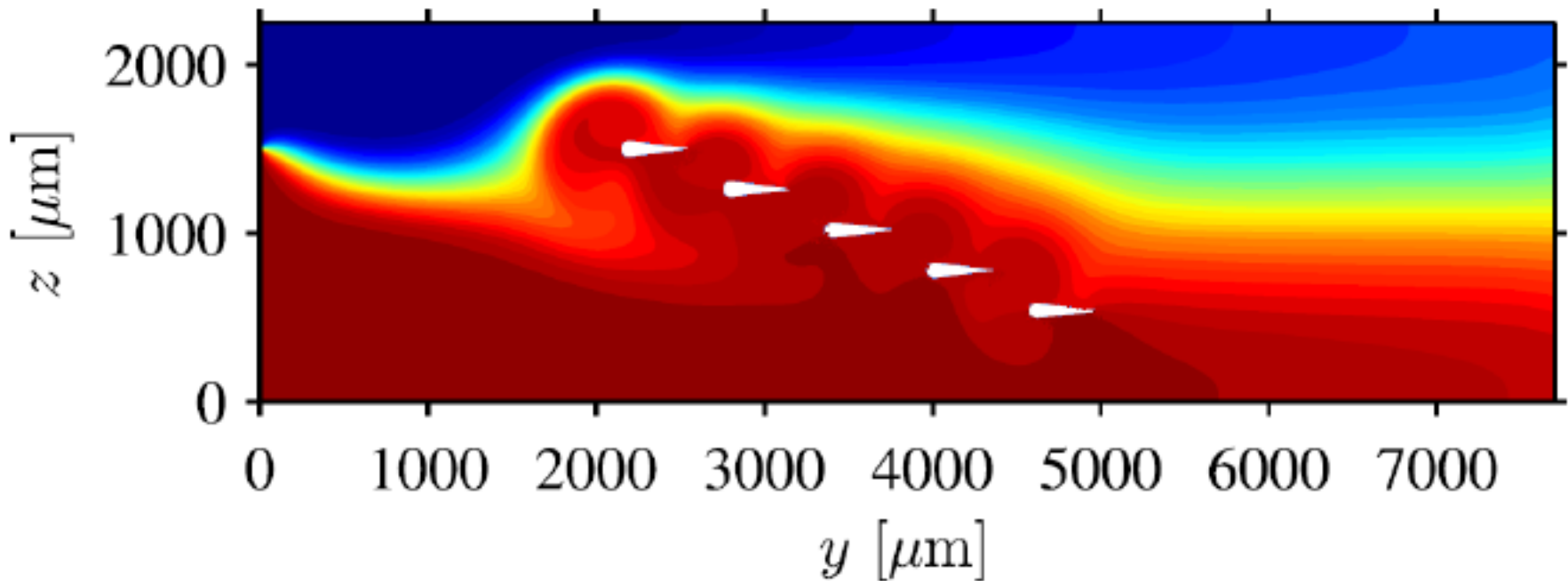
Streaming from the opposite edges suppresses each other.

## Larger Sharp-Edges



Larger edges effectively perturbs both the incoming streams.

# Concentration gradient



- The gradient profile can be spatially controlled by changing the arrangement of the sharp-edged structures.
- The gradient profile can be temporally controlled by tuning the inlet velocity or/and the applied power.
- Useful for studying temporal dynamics of cells in a chemical environment.

# Conclusion and Outlook

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- A numerical model for sharp-edge based mixing is presented with good qualitative comparison with the experiments.
- The effects of operational and geometrical parameters was investigated.
- The exact displacement profile at the walls need to be further investigated.
- Quantitative 3D Astigmatism Particle Tracking Velocimetry (APT<sub>V</sub>) measurements for the experimental verification are in progress.



# Acknowledgments

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Po-Hsun Huang



Tony Jun Huang



Francesco Costanzo



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